## ROLLON <br> BY TIMKEN

## Plus System

SC Series

## New Plus System

It simplifies the project, improves the perfomance and reduces the application cost: 8 main advantages.

- Avoid costs related to engineering, manufacturing and testing a self-made solution.
- Eliminate all potential risks related to reliability and lack of warranties with one trusted partner.
- Focus your efforts on your core business.



## New Plus System - SC

- Fixed carriage and movable profile for Z-Axes solutions, with omega belt driving system.
- Joinable extension to reach the desired length regardless of the stroke.
- Predisposition for assembling the clampling element
- Monoblock and lightened driving head for greater precision, realiability and dynamics.
- Through passing profile protects the cables.
- Easy and fast assembly of accessories at the end of the arm improves productivity.


Low maintenance

Special lubrication tanks ensure continuous greasing of the ball raceways up to 5000 km .

## High

 productivityHigh quality design ensures high dynamics with stressful duty cycles: speed up to $5 \mathrm{~m} / \mathrm{s}$, acceleration up to $50 \mathrm{~m} / \mathrm{s}^{2}$.


Good repeatability accuracy

Up to $\pm 0.05 \mathrm{~mm}$.

## Ideal for multi-axes systems

A dedicated set of accessories allows easy assembly to achieve high performance $X-Y-Z$ multiaxis systems.

ROBOT and SC series are designed to be compatible and assembled without the need for adapter plates.

## SC series

## SC series description



Fig. 45

## SC

The SC series linear unit is specifically designed for vertical motion in gantry applications, or in applications where the aluminum profile must move while the carriage remains fixed. It is available in three sizes: 100, 130 and 160 mm .

SC is a rigid vertical system, ideal for heavy loads and high cycle applications, thanks to the engineered combination of a self-supporting extruded and anodized aluminum profile and two parallel recirculating ball guides with four low maintenance ball bearing blocks.

The connecting plate at end of the arm allows simple and fast switch of the accessories, reducing downtime and improving the system productivity. It can also accomodate a special extension system (available as optional) which is useful for reaching lengths longer than the maximum stroke and to make the system modular. The extension is fast and easy to assemble and center with precision on the connecting plate, thanks to self-centering keys.

This unit is also designed and configured to be compatible and assembled with the ROBOT series actuators without the need for adapter plates, to create high performance multi-axes systems easily and quickly.

## Corrosion resistant version

All Plus System series of linear actuators are available with stainless steel elements, for applications in harsh environments and/or subject to frequent washes.

The Plus System linear units are constructed using extruded anodized 6060 and 6082 Anti-Corrosive Aluminum, which houses bearings, linear rails, nuts and bolts and components, all of which are made of low carbon SS AISI 303 and 404C steel, to prevent or delay corrosion caused by humidity experienced in the environments where the linear units are used.

Special no-deposit surface treatments are combined with a food grade lubrication system to allow use in highly sensitive applications, such as the food and pharmaceutical industries where product contamination is prohibited.

- Internal stainless steel elements
- Anodized 6060 and 6082 Anti-Corrosive Aluminum Profile
- Very low carbon SS AISI 303 and 404C steel linear rails, nuts and bolts and components
■ Lubricated with organic food grade vegetable oils


## > The components

## Extruded profile

The anodized aluminum extrusions used for the profile of the Rollon SC series linear units were designed and manufactured by industry experts to optimize weight while maintaining mechanical strength. The anodized aluminum alloy 6060 used (see physical-chemical characteristics below) was extruded with dimensional tolerances complying with EN 755-9 standards.
Side slots are provided for fast, trouble-free mounting of accessories (proximity switch runner, etc.). Power cables and/or air hoses (gripper, etc.) can be passed inside the body.

## Driving belt

The Rollon SC series linear units use steel reinforced polyurethane drive belt with AT pitch. This belt is ideal due to its high load transmission characteristics, compact size and low noise. Used in conjunction with a backlash-free pulley, smooth alternating motion can be achieved.

Optimization of the maximum belt width/body dimension ratio enables the following performance characteristics to be achieved:

- High speed
- Low noise

Low wear

## Carriage

The carriage is an enveloping structure that houses the entire linear motion system consisting of a drive pulley and two driven pulleys. The external parts are made of anodized aluminum. Dimensions vary according to type. The carriage is designed to allow the assembly of the SC and ROBOT actuators without the need for adapter plates, to create multi-axes systems easily (see page PLS-48). The carriage also houses brush seals to remove contaminants from the system.

## General data about aluminum used: AL 6060

Chemical composition [\%]

| AI | Mg | Si | Fe | Mn | Zn | Cu | Impurites |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Remaining | $0.35-0.60$ | $0.30-0.60$ | 0.30 | 0.10 | 0.10 | 0.10 | $0.05-0.15$ |

Physical characteristics

| Density | Coeff. of elasticity | Coeff. of thermal expansion $\left(20^{\circ}-100^{\circ} \mathrm{C}\right)$ | Thermal conductivity $\left(20^{\circ} \mathrm{C}\right)$ | Specific heat $\left(0^{\circ}-100^{\circ} \mathrm{C}\right)$ | Resistivity | Melting point |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| kg | kN | $10^{-6}$ | W | J | $\Omega . \mathrm{m} .10^{-9}$ | ${ }^{\circ} \mathrm{C}$ |
| dm ${ }^{3}$ | $\mathrm{mm}^{2}$ | K | m. K | kg. K |  |  |
| 2.7 | 69 | 23 | 200 | 880-900 | 33 | 600-655 |

Mechanical characteristics

| Rm | Rp (02) | A | HB |
| :---: | :---: | :---: | :---: |
| $\frac{\mathrm{N}}{\mathrm{mm}^{2}}$ | $\frac{\mathrm{~N}}{\mathrm{~mm}^{2}}$ | $\%$ | - |
| 205 | 165 | 10 | $60-80$ |

## > The linear motion system

The linear motion system has been designed to meet the load capacity, speed, and maximum acceleration conditions of a wide variety of applications.

## SC series with ball bearing guides

- Two ball bearing guides with high load capacity are mounted in two dedicated seats on the outer sides of the aluminum body.
- The carriage of the linear unit is assembled on four pre-loaded ball bearing blocks with plastic retention cages.
- The four ball row configuration enables the carriage to withstand loading in the four main directions.
- The four blocks have seals on both sides and, where necessary, an additional scraper can be fitted for very dusty conditions.
- Lubrication reservoirs (pockets) installed on the front of the ball bearing blocks supply the right amount of grease, thus promoting long maintenance intervals.


## The linear motion system described above offers:

- High speed and acceleration
- High load capacity
- High permissible bending moments
- Low friction
- Long life
- Low noise
- Free maintenance (dependent on application)


## SC section



Fig. 46

## > The new driving head

The new driving head is designed to allow high freedom while sizing the application and mounting the gearbox on the SC series linear actuators. With the new head, it is possible to assembly the gearbox on either the right or the left side of the actuator by means of a standard assembly kit.

The assembly kit includes: shrink disk; adapter plate and fixing hardware; and can be ordered with the actuator. Different kits are available to accomodate gearboxes from the major brands on the market. For more information see pag. PLS-45.

The same logic is valid when mounting the shaft to connect two units in parallel.

SC 100

SC 100 Dimensions


The length of the safety stroke is provided on request according to the customer's specific requirements.

## Technical data

|  | Type |
| :--- | :---: |
|  | SC 100 |
| Max. useful stroke length [mm] | 1500 |
| Max. positioning repeatability [mm] | $\pm 0.05$ |
| Max. speed [m/s] | 5.0 |
| Max. acceleration [m/s²] | 50 |
| Type of belt | 32 AT 5 |
| Type of pulley | Z 32 |
| Pulley pitch diameter [mm] | 50.93 |
| Carriage displacement per pulley turn [mm] | 160 |
| Carriage weight [kg] | 8.1 |
| Zero travel weight [kg] | 13 |
| Weight for $\mathbf{1 0 0} \mathbf{~ m m ~ u s e f u l ~ s t r o k e ~ [ k g ] ~}$ | 0.9 |
| Starting torque [Nm] | 1.3 |
| Rail size [mm] | 15 |

Moments of inertia of the aluminum body

| Type | $I_{x}^{\prime}$ <br> $\left[10^{7} \mathrm{~mm}^{4}\right]$ | $\mathrm{I}_{\mathrm{y}}$ <br> $\left[10^{7} \mathrm{~mm}^{4}\right]$ | $\mathrm{I}_{\mathrm{p}}$ <br> $\left[10^{7} \mathrm{~mm}^{4}\right]$ |
| :--- | :---: | :---: | :---: |
| SC 100 | 0.05 | 0.23 | 0.28 |

## Driving belt

The driving belt is manufactured from a friction resistant polyurethane and with steel cords for high tensile stress resistance.

| Type | Type of <br> belt | Belt width <br> $[\mathrm{mm}]$ | Weight <br> $[\mathrm{kg} / \mathrm{m}]$ |
| :--- | :---: | :---: | :---: |
| SC 100 | 32 AT 5 | 32 | 0.105 |

Belt length $(\mathrm{mm})=L+77$


Load capacity

| Type | $\begin{aligned} & \mathrm{F}_{\mathrm{x}} \\ & {[\mathrm{~N}]} \end{aligned}$ |  | $\begin{aligned} & F_{y} \\ & {[N]} \end{aligned}$ |  | $\begin{aligned} & \mathrm{F}_{2} \\ & {[\mathrm{~N}]} \end{aligned}$ | $\begin{gathered} M_{x} \\ {[\mathrm{Nm}]} \end{gathered}$ | $\begin{gathered} M_{y} \\ {[\mathrm{Nm}]} \end{gathered}$ | $\begin{gathered} M_{r} \\ {[\mathrm{Nm}]} \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stat. | Dyn. | Stat. | Dyn | Stat. | Stat. | Stat. | Stat. |
| SC 100 | 1080 | 883 | 96800 | 45082 | 96800 | 5469 | 11713 | 11713 |

See verification under static load and lifetime on page SL-2 and SL-3
$F_{x}$ in the table represents the maximum capacity of the toothed belt. For the application, the limit of transmittable torque of the shrink disk must be considered too (see page PLS-45).

SC 130

SC 130 Dimensions


The length of the safety stroke is provided on request according to the customer's specific requirements.
Fig. 48

## Technical data

|  | Type |
| :---: | :---: |
|  | SC 130 |
| Max. useful stroke length [mm] | 2000 |
| Max. positioning repeatability [mm]*1 | $\pm 0.05$ |
| Max. speed [m/s] | 5.0 |
| Max. acceleration [ $\mathrm{m} / \mathrm{s}^{2}$ ] | 50 |
| Type of belt | 50 AT 10 |
| Type of pulley | Z 21 |
| Pulley pitch diameter [mm] | 66.84 |
| Carriage displacement per pulley turn [mm] | 210 |
| Carriage weight [kg] | 13.8 |
| Zero travel weight [kg] | 23.6 |
| Weight for 100 mm useful stroke [kg] | 1.4 |
| Starting torque [ Nm ] | 3 |
| Rail size [mm] | 15 |

## Moments of inertia of the aluminum body

| Type | $I^{\mathrm{x}}$ <br> $\left[10^{7} \mathrm{~mm}^{4}\right]$ | $\left.\mathrm{I}_{\mathrm{y}}^{\mathrm{y}} \mathrm{mm}^{4}\right]$ | $\mathrm{I}_{\mathrm{p}}$ <br> $\left[10^{7} \mathrm{~mm}^{4}\right]$ |
| :--- | :---: | :---: | :---: |
| SC 130 | 0.15 | 0.65 | 0.79 |

## Driving belt

The driving belt is manufactured from a friction resistant polyurethane and with steel cords for high tensile stress resistance.

| Type | Type <br> of belt | Belt width <br> $[\mathrm{mm}]$ | Weight <br> $[\mathrm{kg} / \mathrm{m}]$ |
| :--- | :---: | :---: | :---: |
| SC 130 | 50 AT 10 | 50 | 0.209 |
|  |  |  | Tab. 91 |

Belt length $(m m)=L+115$


Load capacity

| Type | $\begin{gathered} \mathrm{F}_{\mathrm{x}} \\ {[\mathrm{~N}]} \end{gathered}$ |  | $\begin{aligned} & F_{y} \\ & {[N]} \end{aligned}$ |  | $\begin{gathered} \mathrm{F}_{2} \\ {[\mathrm{~N}]} \end{gathered}$ | $\begin{gathered} \mathrm{M}_{\mathrm{x}} \\ {[\mathrm{Nm}]} \end{gathered}$ | $\begin{gathered} M_{y} \\ {[\mathrm{Nm}]} \end{gathered}$ | $\begin{gathered} \mathrm{M}_{2} \\ {[\mathrm{Nm}]} \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stat. | Dyn. | Stat. | Dyn | Stat. | Stat. | Stat. | Stat. |
| SC 130 | 3943 | 2446 | 96800 | 45082 | 96800 | 6921 | 16311 | 16311 |

See verification under static load and lifetime on page SL-2 and SL-3
$F_{x}$ in the table represents the maximum capacity of the toothed belt. For the application, the limit of transmittable torque of the shrink disk must be considered too (see page PLS-45).

SC 160

SC 160 Dimensions


The length of the safety stroke is provided on request according to the customer's specific requirements.
Fig. 49

## Technical data

|  | Type |
| :---: | :---: |
|  | SC 160 |
| Max. useful stroke length [mm] | 2500 |
| Max. positioning repeatability [mm] ${ }^{* 1}$ | $\pm 0.05$ |
| Max. speed [m/s] | 5.0 |
| Max. acceleration [ $\mathrm{m} / \mathrm{s}^{2}$ ] | 50 |
| Type of belt | 70 AT 10 |
| Type of pulley | Z 22 |
| Pulley pitch diameter [mm] | 70.03 |
| Carriage displacement per pulley turn [mm] | 220 |
| Carriage weight [kg] | 24.9 |
| Zero travel weight [kg] | 39.9 |
| Weight for 100 mm useful stroke [kg] | 1.8 |
| Starting torque [ Nm ] | 6.1 |
| Rail size [mm] | 20 |

${ }^{* 1}$ ) Positioning repeatability is dependent on the type of transmission used

Load capacity

| Type | $\begin{aligned} & F_{x} \\ & {[N]} \end{aligned}$ |  | $\begin{aligned} & \mathbf{F}_{\mathrm{v}} \\ & {[\mathrm{~N}]} \end{aligned}$ |  | $\begin{aligned} & \mathrm{F}_{2} \\ & {[\mathrm{~N}]} \end{aligned}$ | $\begin{gathered} \mathrm{M}_{\mathrm{x}} \\ {[\mathrm{Nm}]} \end{gathered}$ | $\begin{gathered} M_{y} \\ {[\mathrm{Nm}]} \end{gathered}$ | $\begin{gathered} M_{2} \\ {[\mathrm{Nm}]} \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stat. | Dyn. | Stat. | Dyn | Stat. | Stat. | Stat. | Stat. |
| SC 160 | 5810 | 3605 | 153600 | 70798 | 153600 | 13555 | 31872 | 31872 |

See verification under static load and lifetime on page SL-2 and SL-3
$\mathrm{F}_{\mathrm{x}}$ in the table represents the maximum capacity of the toothed belt. For the application, the limit of transmittable torque of the shrink disk must be considered too (see page PLS-45).
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## Moments of inertia of the aluminum body

| Type | $\mathrm{I}_{\mathrm{x}}$ <br> $\left[10^{7} \mathrm{~mm}^{4}\right]$ | $\mathrm{I}_{\mathrm{y}}$ <br> $\left[10^{7} \mathrm{~mm}^{4}\right]$ | $\mathrm{I}_{\mathrm{p}}$ <br> $\left[\mathbf{1 0}^{7} \mathrm{~mm}^{4}\right]$ |
| :--- | :---: | :---: | :---: |
| SC 160 | 0.383 | 1.313 | 1.696 |

## Driving belt

The driving belt is manufactured from a friction resistant polyurethane and with steel cords for high tensile stress resistance.

| Type | Type <br> of belt | Belt width <br> $[\mathrm{mm}]$ | Weight <br> $[\mathrm{kg} / \mathrm{m}]$ |
| :--- | :---: | :---: | :---: |
| SC 160 | 70 AT 10 | 70 | 0.407 |

Belt length $(\mathrm{mm})=L+106$


Tab. 93

## > End-of-arm connecting plate

The connecting plate at end of the arm allows simple and fast switch of the accessories, reducing downtime and improving the system productivity. It can also accomodate a special extension system (available as optional) which is useful for reaching lengths longer than the maximum stroke and to make the system modular. The extension is fast and easy to assemble and center with precision on the connecting plate, thanks to self-centering keys.

## Lubrication

## SP linear units with ball bearing guides

SP Linear units are equipped with self lubricating linear ball guides. The ball bearing carriages of the SP versions are also fitted with a retention cage that eliminates "steel-steel" contact between adjacent revolving parts and prevents misalignment of these in the circuits.
Special lubrication reservoirs are mounted on the front plates of the linear blocks which continuously provide the necessary amount of grease to the ball raceways under load. These lubrication reservoirs also considerably reduce the frequency of lubrication of the module. This system guarantees a long interval between maintenances: SP version: every 5000 km or 1 year of use, based on the value reached first. If a longer service life is required or in case of high dynamic or high loaded applications please contact our offices for further verification.


Fig. 51

- Insert the tip of the grease gun in the specific grease blocks.
- For lubrication of linear units use lithium soap grease NLGI 2.
- For specially stressed applications or difficult enviromental conditions, lubrication should be carried out more frequently. Refer to Rollon for further advice.

Quantity of lubricant necessary for re-lubrication of each block:

| Type | Unit: $\left[\mathrm{cm}^{3}\right]$ |
| :--- | :---: |
| SC 100 | 0.7 |
| SC 130 | 0.7 |
| SC 160 | 1.4 |

Fig. 50
SC160
Keyway A-B: 10X8X40


Tab. 97
> Hollow shafts
Hollow shaft type AC - Standard supply


| Appliable <br> to unit | Shaft <br> type | D3 | D1 | D2 | A X B | D4 | F |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SC 100 | AC 34 | 34 H8 | - | 96 | - | 62 | M6 |
| SC 130 | AC 41 | 41 H8 | 100 | - | $92 \times 72$ | 72 | M6 |
| SC 160 | AC 50 | 50 H8 | 130 | 154 | - | 95 | M8 |

## > Arm extension

The extension system allows to optimize and unify the stroke of the vertical axis, expecially when part of a multi-axis system, and to reach lengths longer than the maximum stroke. Thanks to dedicated connecting plates, it is easy to assemble and center with precision.

Upon delivery, Rollon provides the extension and the self-centering keys to properly connect it the main axis body. Screws to connect the accessories at the end of the extension must be bought separately.

The dimensions of the connecting plate at the end of the extension are the same of the plate at the end of the axis arm, as shown on pg. PLS-41.

| Appliable <br> to unit | L min. <br> $[\mathrm{mm}]$ | L max <br> $[\mathrm{mm}]$ |
| :--- | :---: | :---: |
| SC 100 | 60 | 1000 |
| SC 130 | 100 | 1000 |
| SC 160 | 100 | 1000 |



## Accessories

## Simple shaft type AS



Position of the simple shaft can be to the left or right of the drive head.

| Unit | Shaft type | B | D1 | AS assembly <br> KIT code |
| :--- | :---: | :---: | :---: | :---: |
| SC 100 | AS 20 | 40 | $20 \mathrm{h7}$ | G003372 |
| SC 130 | AS 25 | 50 | $25 h 7$ | G003375 |
| SC 160 | AS 25 | 50 | $25 h 7$ | G000649 |

Tab. 100

Dedicated pneumatic clamping elements are available for every size of the SC linear units. The slots for installation are located on the left and right side of the carriage, one per side.

The clamp kit provided by Rollon includes: clamp, fixing screws and air port. It must be ordered separetely from the actuator using the code on Tab. 101. For size 100 the clamp must be requested on order and the actuator can be delivered only with the clamp assembled by Rollon. For size 130 and 160 Rollon can assemble the kit on the actuator if the unit is ordered with the head code 1RZ (see Ordering Key pg. PLS-47), otherwise the kit can be delivered as separate item and assembled later.

Pneumatic clamping elements


Fig. 55

To properly function, the system must be connected to air pressure supply ( 6 bars). When the air supply is cut, the clamping elements close on the two rails with the total clamping force shown in the table below.

| Unit | Item code | Clamping force <br> $[\mathrm{N}]$ |
| :--- | :---: | :---: |
| SC 100 | G003495 | 800 |
| SC 130 | G003495 | 800 |
| SC 160 | G003496 | 1200 |

Tab. 101

## T-nuts



Fig. 56
Steel nuts to be used in the slots of the body

Fixing by T-nuts


## Warning:

Do not fix the linear units through the drive ends.


Proximity


Fig. 58

Fitting of the proximity switch
Proximity switches can be mounted on threaded mounting holes that are positioned on the sides of the carriage. Do not over-torque the switches during installation as this can cause interference with the proximity switch runner and damage the sensor.

## Sensor dog

L-shaped bracket in zinc-plated iron, mounted on the carriage and used for proximity switch operations.

| Unit | B4 | H4 | L4 | Sensor dog <br> Code |
| :--- | :---: | :---: | :---: | :---: |
| SC 100 | 8.5 | 23 | 50 | G003346 |
| SC 130 | 8.4 | 25 | 50 | G001862 |
| SC 160 | 10 | 27 | 50 | G003459 |

Tab. 103

## Gearbox assembly kit



Fig. 59

Codes on the the table below refer to the gearbox assembly kit.
The kit includes: shrink disk; adapter plate; fixing hardware.

| Unit type | Gearbox type (not included) | Kit Code |
| :---: | :---: | :---: |
| SC100 | MP080 | G000529 |
|  | PE3; LP070; LC070 | G000530 |
|  | MP060; PLE060 | G000531 |
|  | SW030 | G000748 |
|  | P3 | G001162 |
| SC130 | P3 | G000824 |
|  | MP080 | G000826 |
|  | LC090; MPV01; NP025S; PE4 | G000827 |
|  | PE3; NP015S; LC070 | G001078 |
|  | SP075; PLN090 | G000859 |
|  | SP060; PLN070 | G000829 |
|  | SW040 | G000866 |
| SC160 | AB115 | G000481 |
|  | MP130 | G000482 |
|  | LC120; MPV02; NP035S; PE5 | G000483 |
|  | LC090; PE4; NP025S | G000525 |
|  | SP075; PLN090;P4 | G000526 |
|  | MP105 | G000527 |
|  | PSF5;NPS35;SP+100 | G000657 |

Single shrink disc


Fig. 60

Codes on the table below refer to a shink disc ordered as single element.

| Unit type | Hollow shaft [mm] | Shrink disc dxD [mm] | Transmittable torque* [Nm] | Shrink disc code |
| :---: | :---: | :---: | :---: | :---: |
| SC100 | 34 | $14 \times 34$ | 64 | 6005737 |
|  |  | $16 \times 34$ | 73 | 6005738 |
|  |  | $19 \times 34$ | 87 | 6005739 |
| SC130 | 41 | $16 \times 41$ | 101 | 6005733 |
|  |  | $19 \times 41$ | 150 | 6005734 |
|  |  | $22 \times 41$ | 174 | 6005735 |
|  |  | $25 \times 41$ | 198 | 6005736 |
| SC160 | 50 | $25 \times 50$ | 286 | 6005730 |
|  |  | $25 \times 50$ | 324 | 6005731 |
|  |  | $32 \times 50$ | 415 | 6005732 |

*Transmiltable torque in the table represents the maximum capacity of the shrink disk.Tab. 105 For the application, the limit of $F_{x}$ must be considered too

For other gearbox type ask Rollon

## > Installation option

The ball bearing guide linear drive systems of Rollon SC series linear units enable support of loads in any direction. They can therefore be installed in any position. even horizontally as per the figure below

Direct fixing


Fig. 61

## Ordering key

 $\checkmark$Identification codes for the SC linear unit


In order to create identification codes for Actuator Line, you can visit: http://configureactuator.rollon.com

## Multiaxis systems

 VPreviously, customers wishing to build multiaxis units have had to design, draw and manufacture all the elements necessary to assemble two or more axis. Rollon now offers a set of fittings including brackets and cross plates, to enable multiaxis units to be built. The SC series is also pre-

## Two axis - X-Y system



A - Linear units: X axis: 2 ELM 80 SP... Y axis: 1 ROBOT 160 SP...
Connection part: 2 kits of fixing brackets for ROBOT 160 SP... on to the carrieages of ELM 80 SP...

Two axis - Y-Z system


## B - Linear units: X axis: 1 ROBOT 220 SP... Z axis: 1 SC 160 Connection part: None

The SC 160 unit is directly assembled on to the ROBOT 220 SP... unit without further elements
engineered to facilitate direct connection with the units of the ROBOT series. In addition to standard elements, Rollon also provides plates for special applications.

## Application examples:

## Three axis - X-Y-Z system



C - Linear units: X axis: 2 ELM 65 SP... Y axis: 1 ROBOT 130 SP... Z axis: 1 SC 65
Connection part: 2 kits of fixing brackets for ROBOT 130 SP... on to the carrieages of ELM 65 SP... The SC 65 unit is directly assembled on to the ROBOT 130 SP... unit without further elements.

Three axis - X-Y-Z system


D - Linear units: X axis: 1 ROBOT 220 SP... Y axis: 1 ROBOT 130 SP... Z axis: SC 65

Connection part: 1 kit of fixing brackets for ROBOT 130 SP... unit to the carriage of the ROBOT 220 SP... unit. The SC 65 unit is directly assembled on to the ROBOT 130 SP... unit without further elements.

